

# Characterization and Validation of Irradiated Vacuum Sensors

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# About myself



Exchange Programme – Singapore



MSc. Quantum Engineering

BEng. Mechanical Engineering



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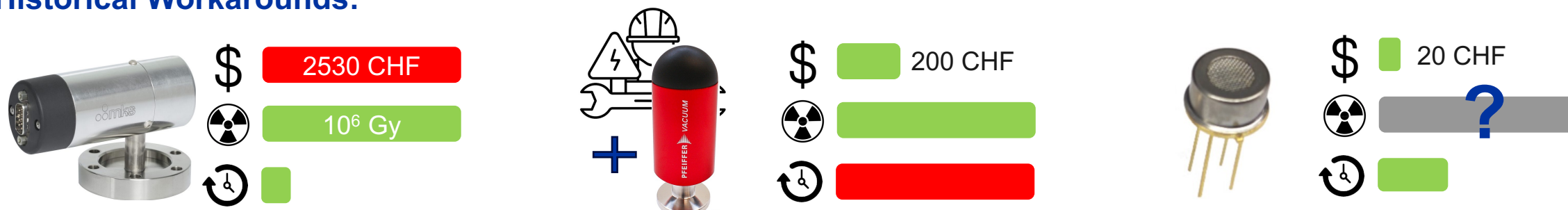


# Project Overview

## Challenge:

- HL-LHC radiation levels 10x higher - need radiation-tolerant vacuum sensors
- Current rad-hard sensors extremely expensive
- New low-cost Pirani Gauges available, but radiation tolerance unknown
- Need validation of performance after radiation exposure

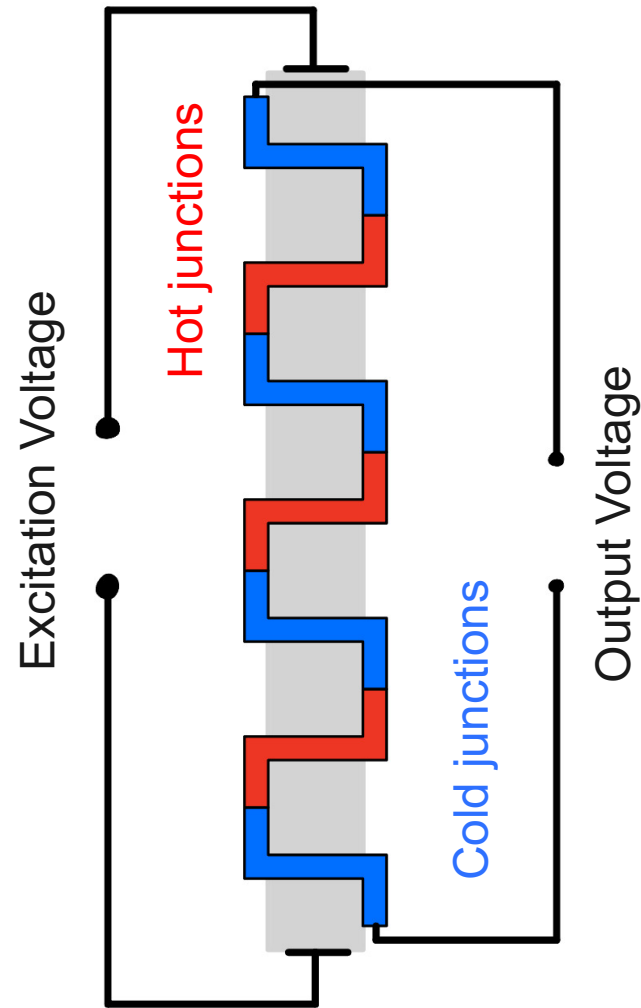
## Historical Workarounds:



## Approach:

Build test setup → Baseline characterization → Controlled irradiation → Evaluate radiation effects

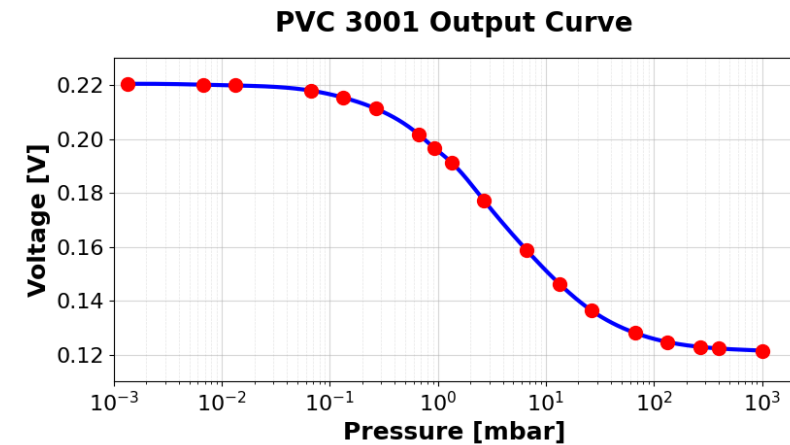
# Thermopiles Working Principle



- Based on Pirani gauge principle: Measures vacuum pressure via gas thermal conductivity
- Resistive heater (1.2 V excitation) dissipates power; heat loss through gas conduction  $\propto$  pressure
- Thermopile (series thermocouples) detects temperature difference ( $\Delta T$ ) between hot heater membrane and cold substrate using Seebeck effect
- Output voltage  $\propto \Delta T$ , which increases at lower pressures (less heat loss); nonlinear S-shaped response



Picture of the Sensor



Calibration Curve according to datasheet <sup>[1]</sup>

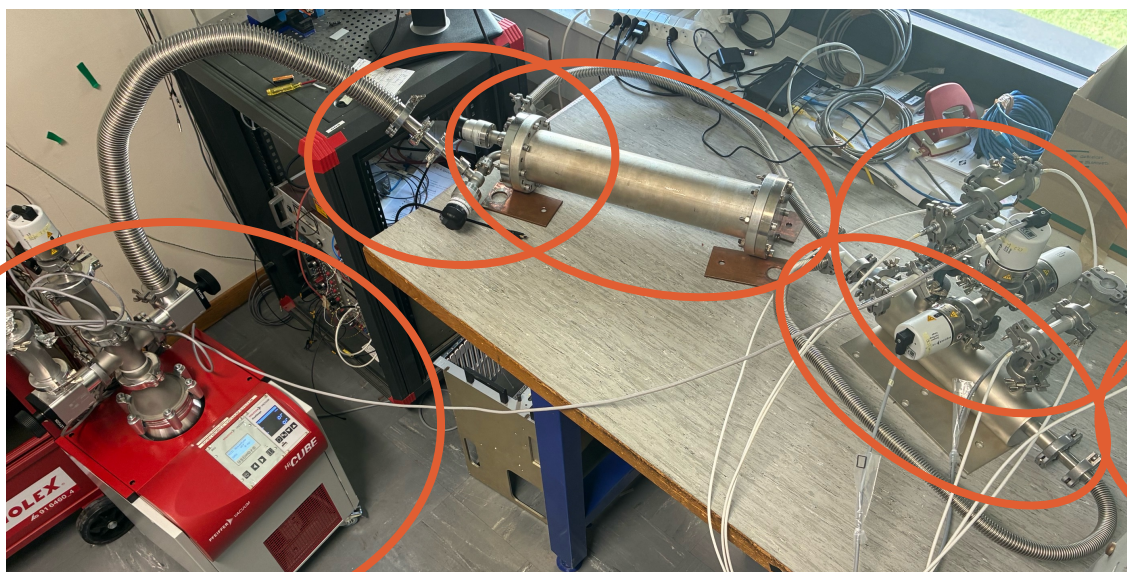
[1] Posifa Technologies. 'Datasheet\_PVC3000\_VaCuum\_ReVC\_C12'. Accessed:2025-08-15. (2021), [Online]. Available: [https://posifatech.com/wp-content/uploads/2022/03/Datasheet\\_PVC3000\\_Vacuum\\_RevC\\_C12.pdf](https://posifatech.com/wp-content/uploads/2022/03/Datasheet_PVC3000_Vacuum_RevC_C12.pdf)



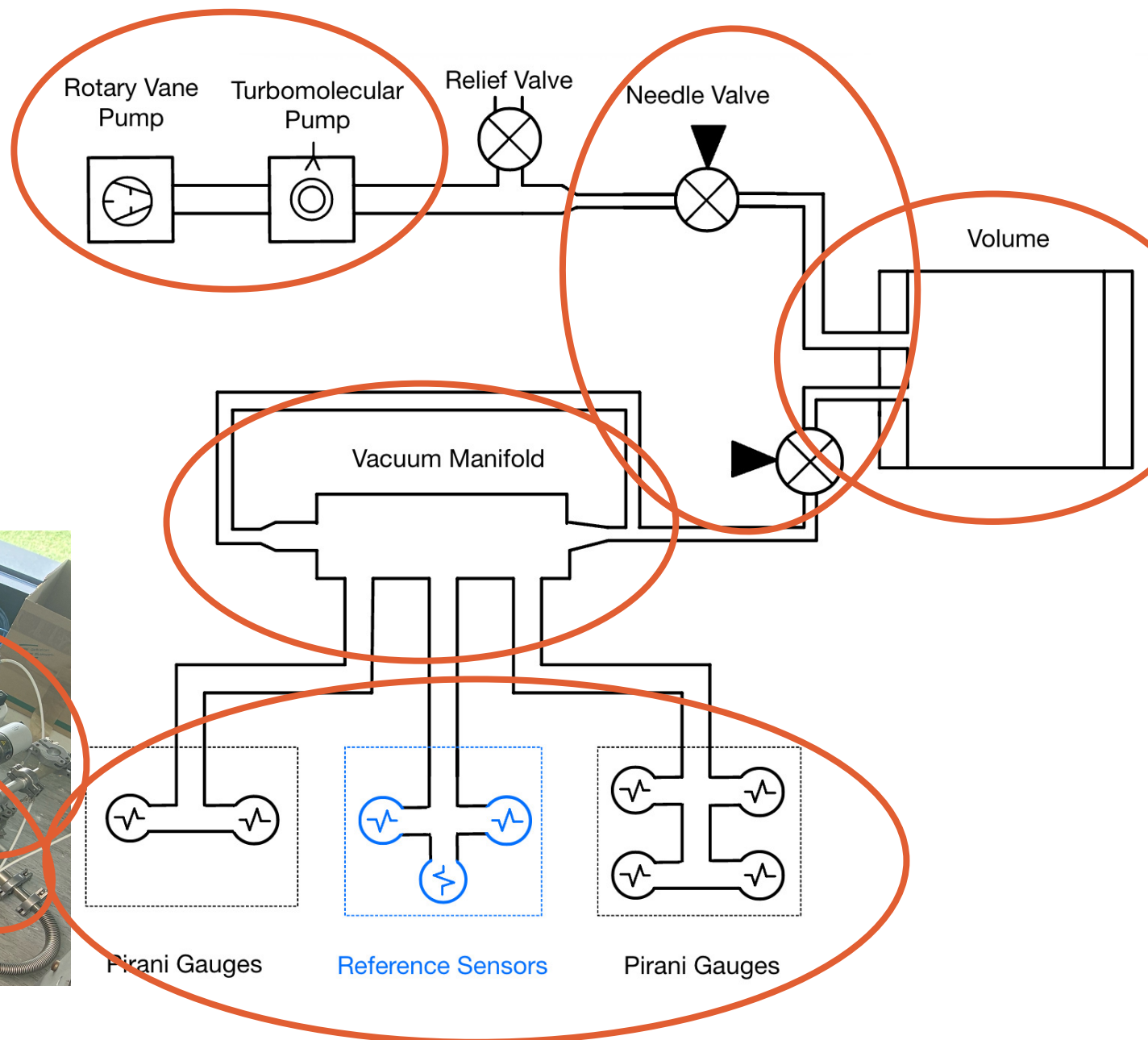
# Vacuum Setup



Cleaning Components in Ultrasonic Cleaner

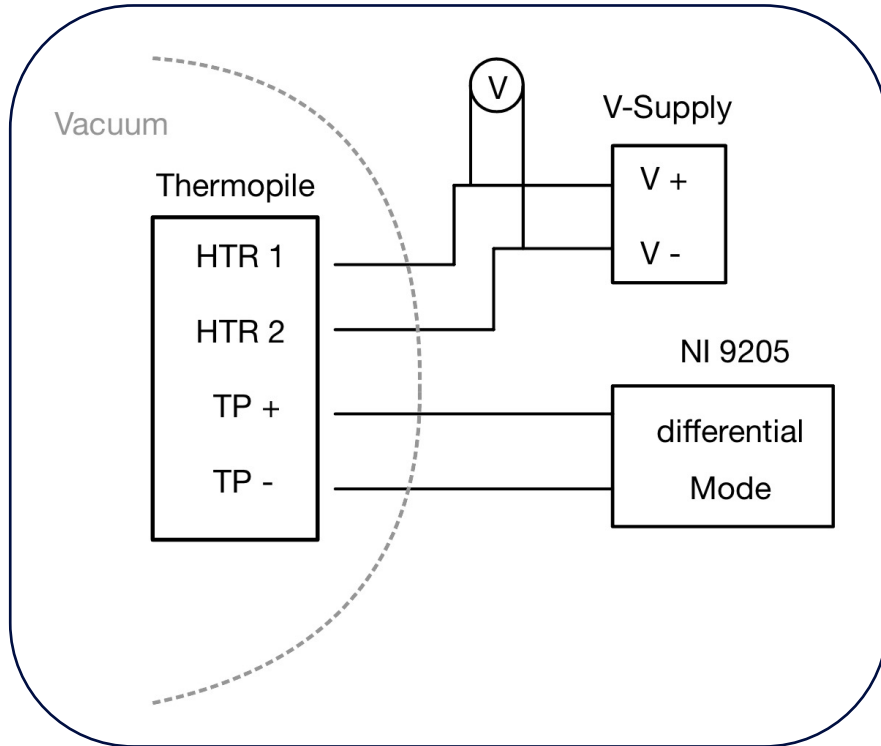


Mounted Setup

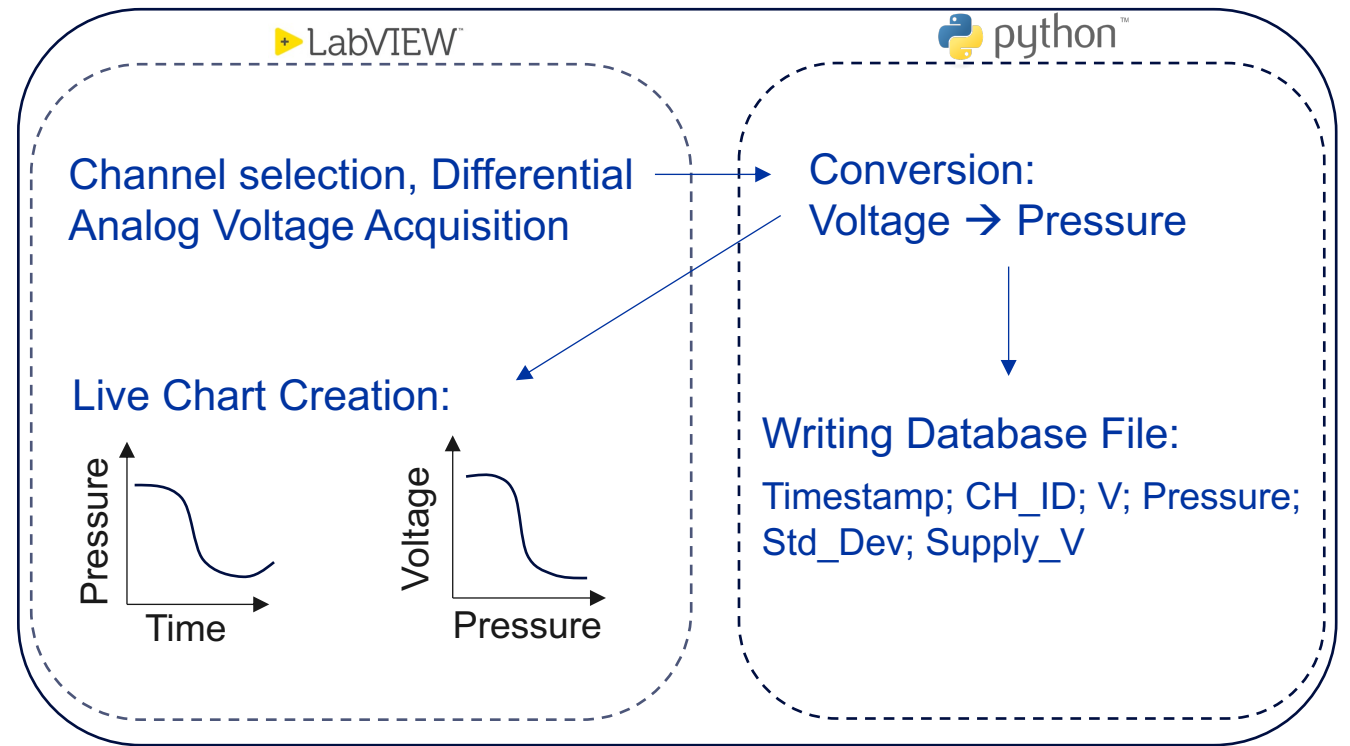


# Readout System

## Hardware Setup

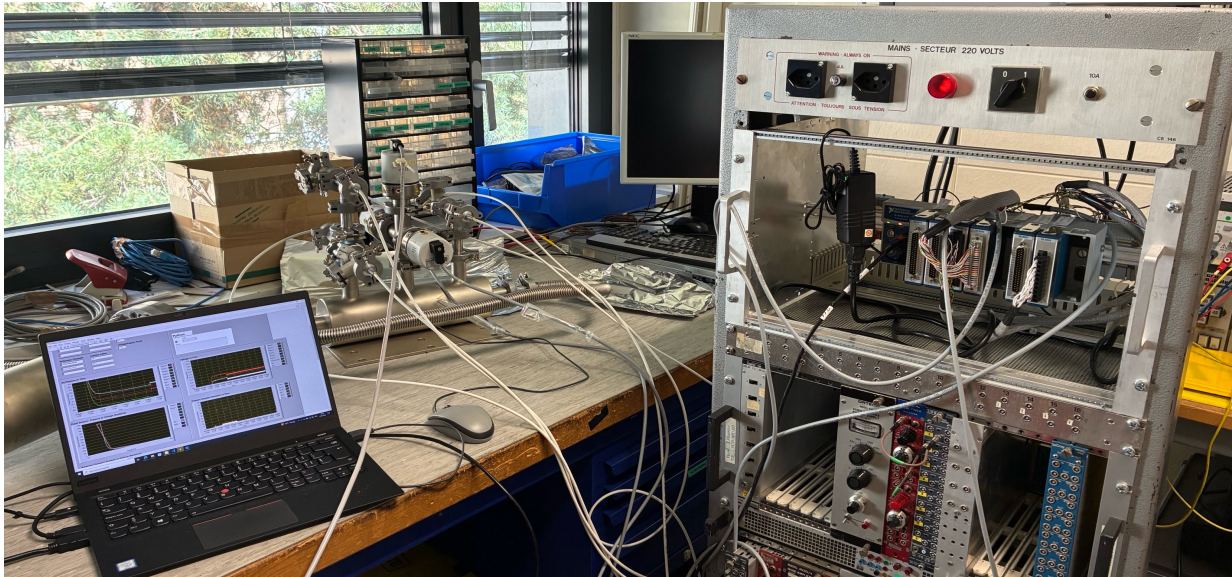


## Live Monitoring and Data Saving

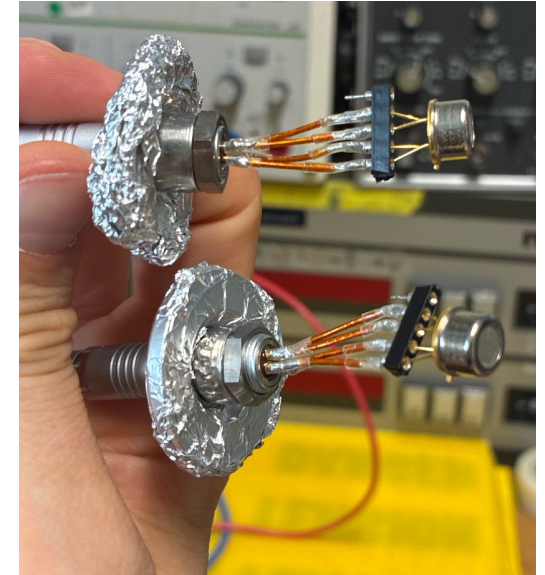




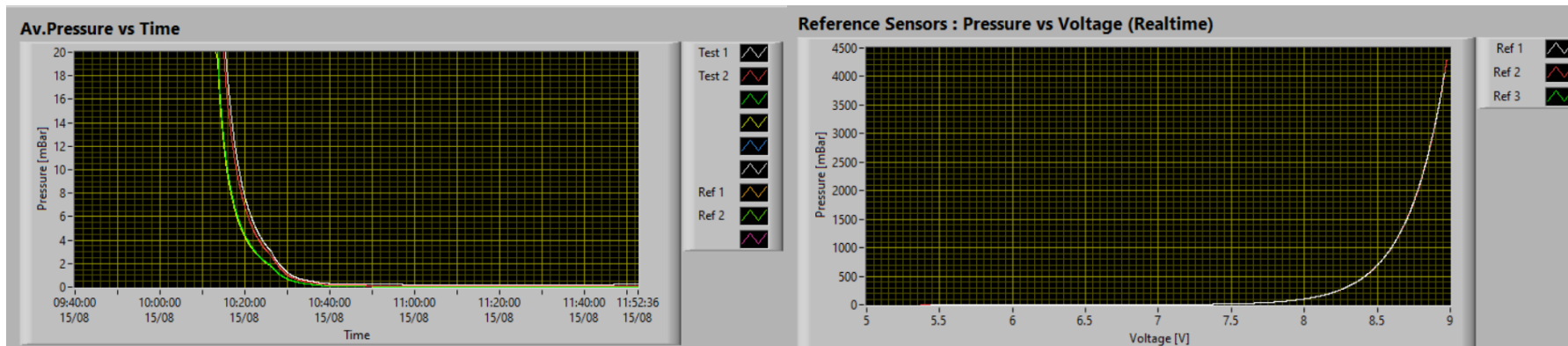
# Readout System



Complete Readout System

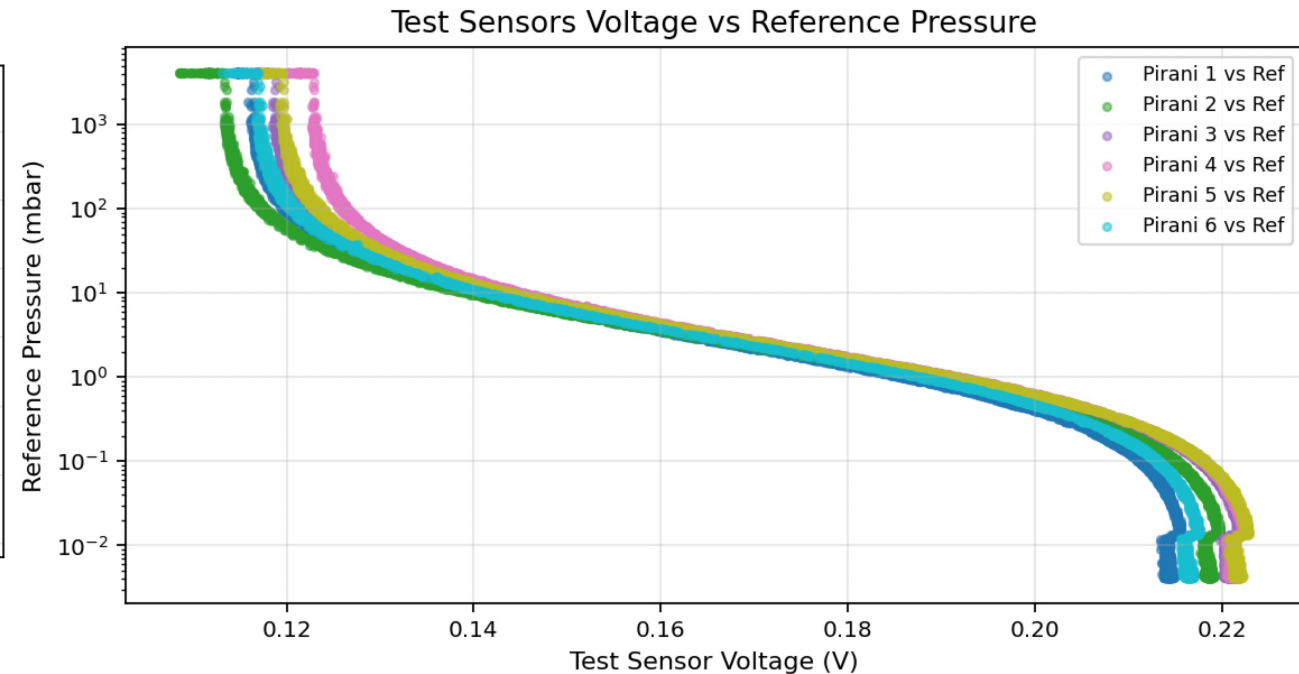
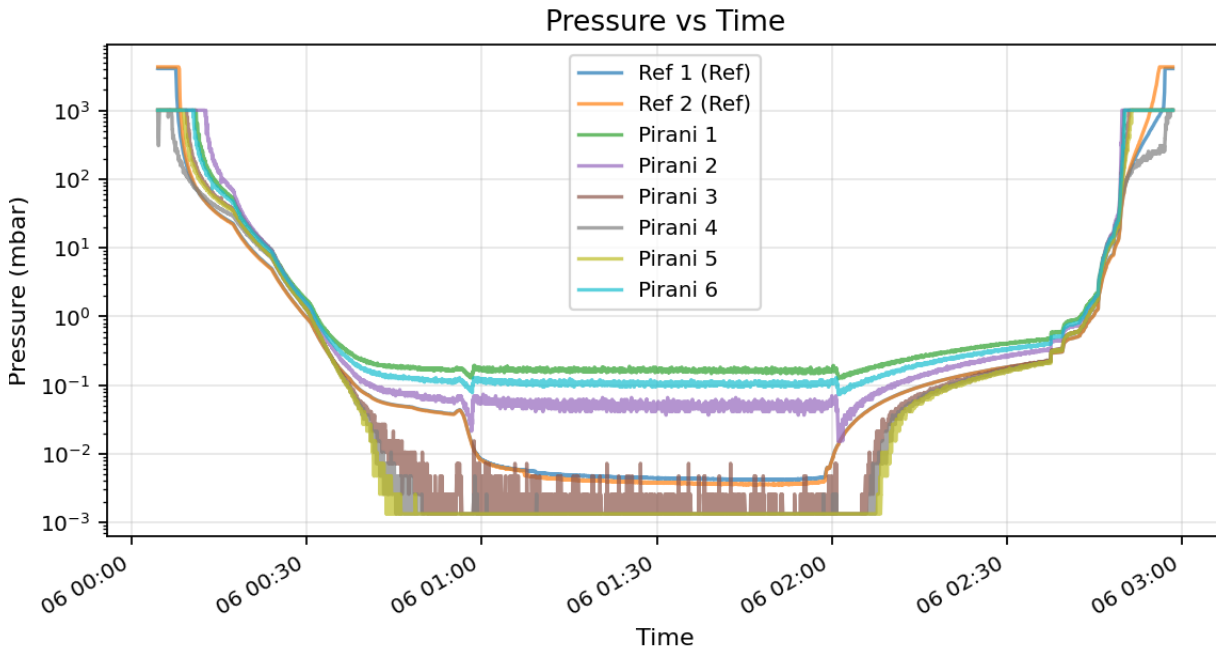


Sensor with feedthrough connector



Live Monitoring of System

# Post-Processing and Analysis



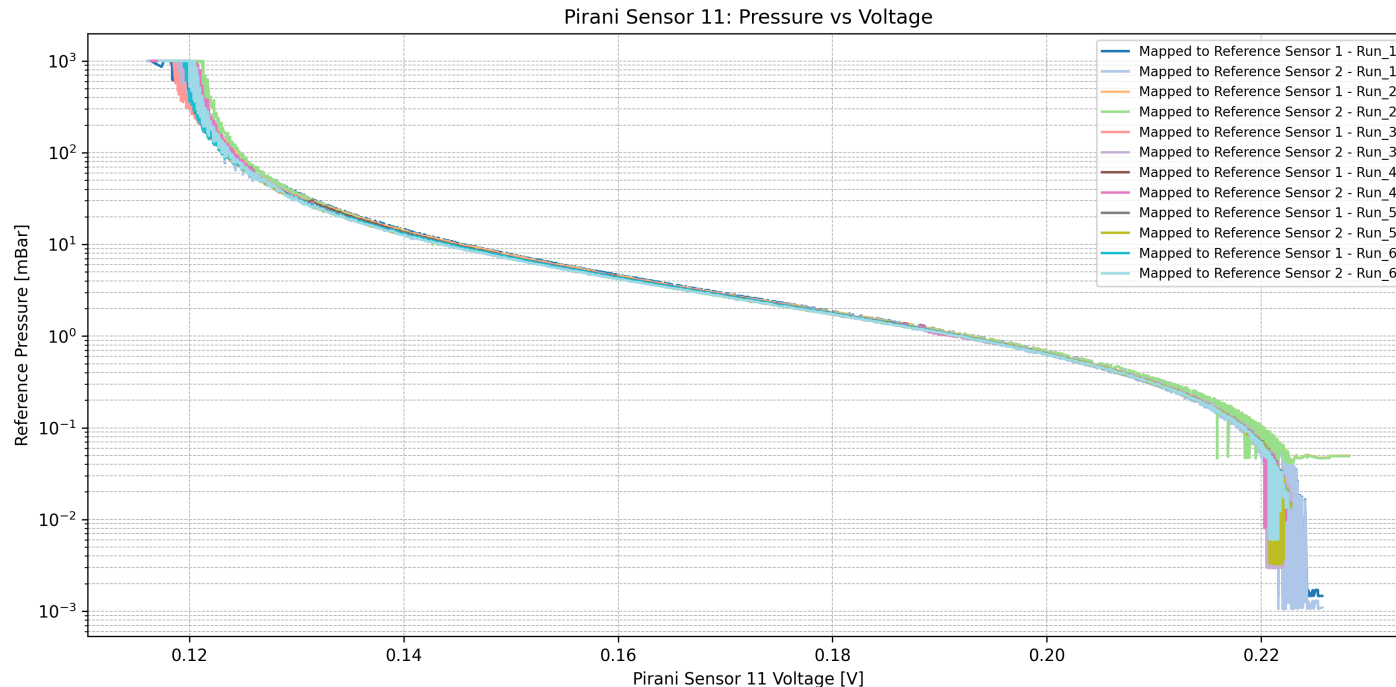
→ Conversion of Datasheet doesn't fit for all sensors

→ Each sensor has a different characteristic

→ Attempt: Try the same sensor across multiple test rounds

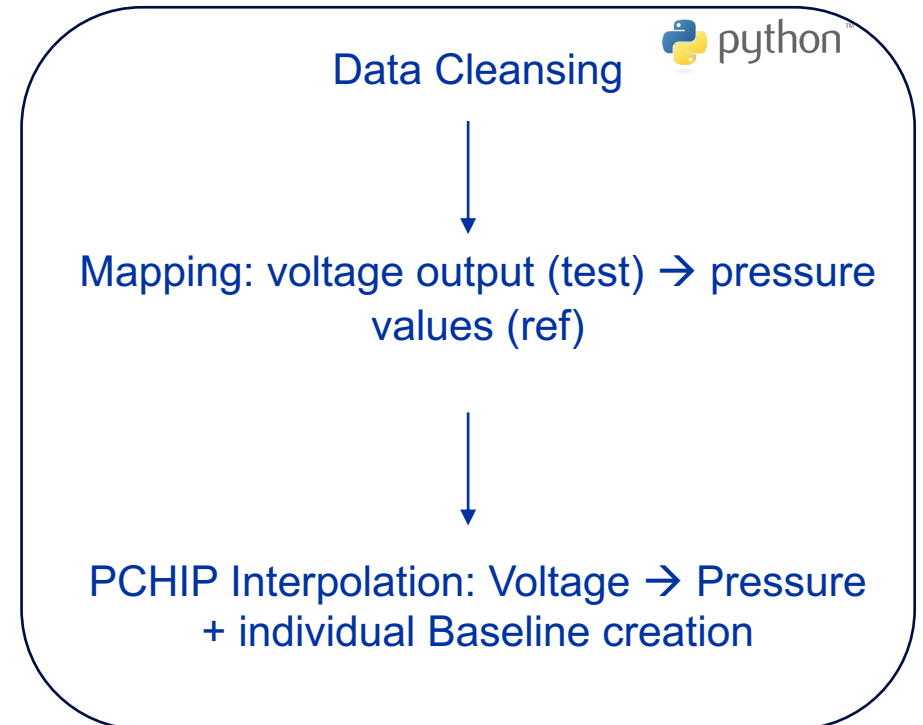
# Characterization before Radiation

But: Sensor output is reproduceable across test runs

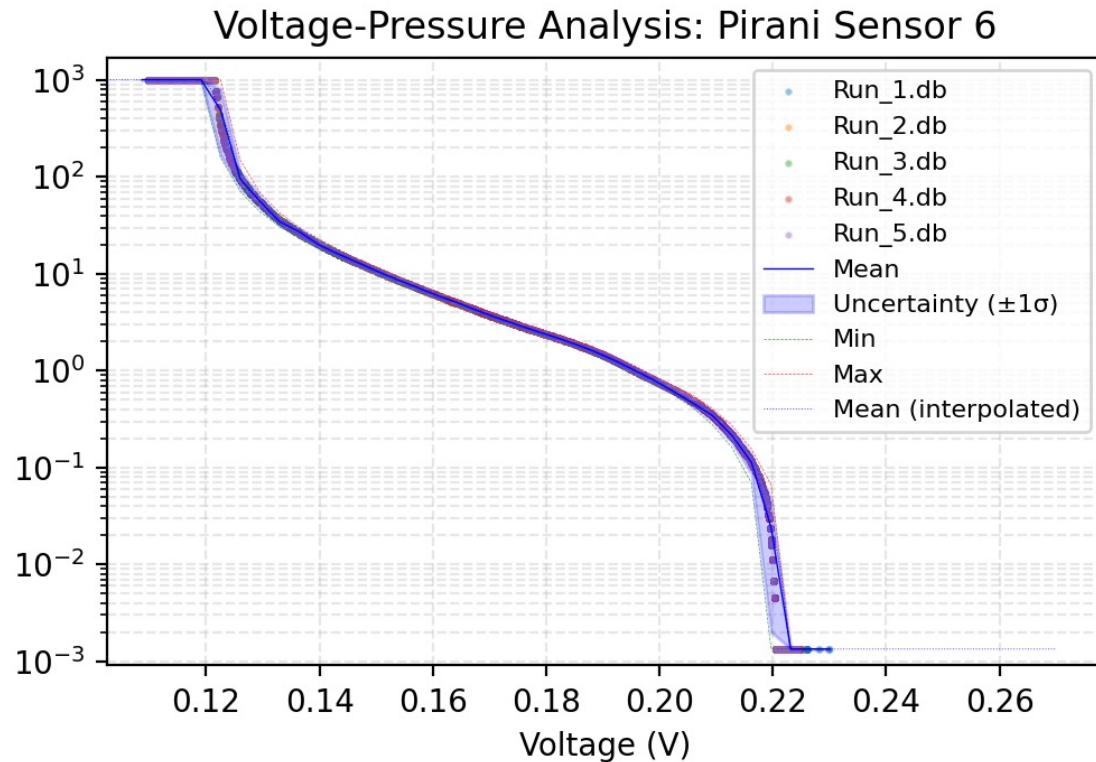


→ Solution: Individual calibration curves for characterization

## Process Overview



# Characterization before Radiation



## Preliminary Baseline Results

### Baseline Establishment:

- Interpolation Baseline including uncertainty function
- Divided in 3 different ranges for better drift detection

### Classification of radiation effects:

- Offset drift → consistently high or low
- Gain drift → sensitivity changes
- Non-linear drift → response curve gets warped
- Noise increase → becomes less precise
- Complete break down

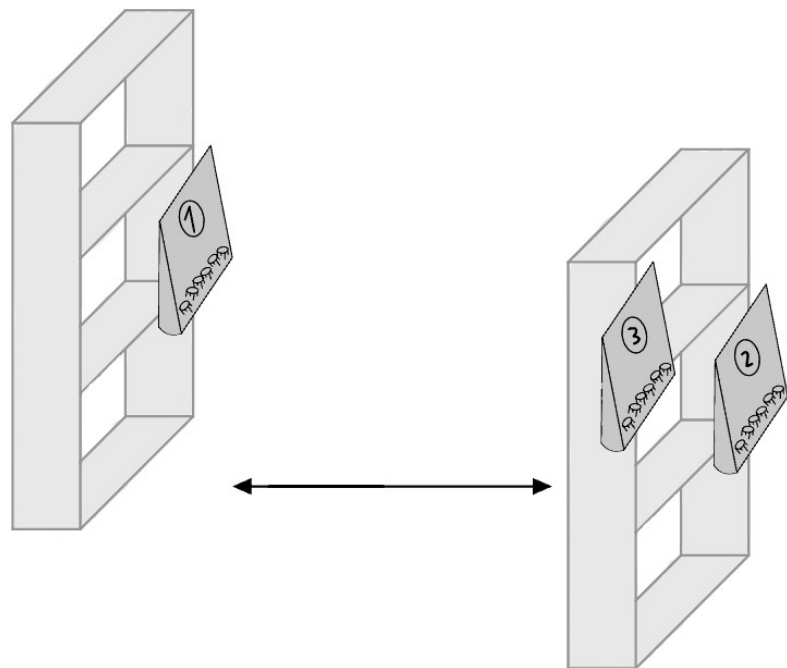
### Acceptance:

- No specified threshold, depends on application



# Radiation Exposure in CHARM

Batches of 6 Sensors each were placed in different positions for certain radiation exposure levels



Proton beam on target  
simulating LHC conditions

Batch	Duration	Radiation Dose
1	1 week	~ 30 Gy
2	1 week	~ 500 Gy
3	3 weeks	~1500 Gy
4	10 weeks	~5000 Gy

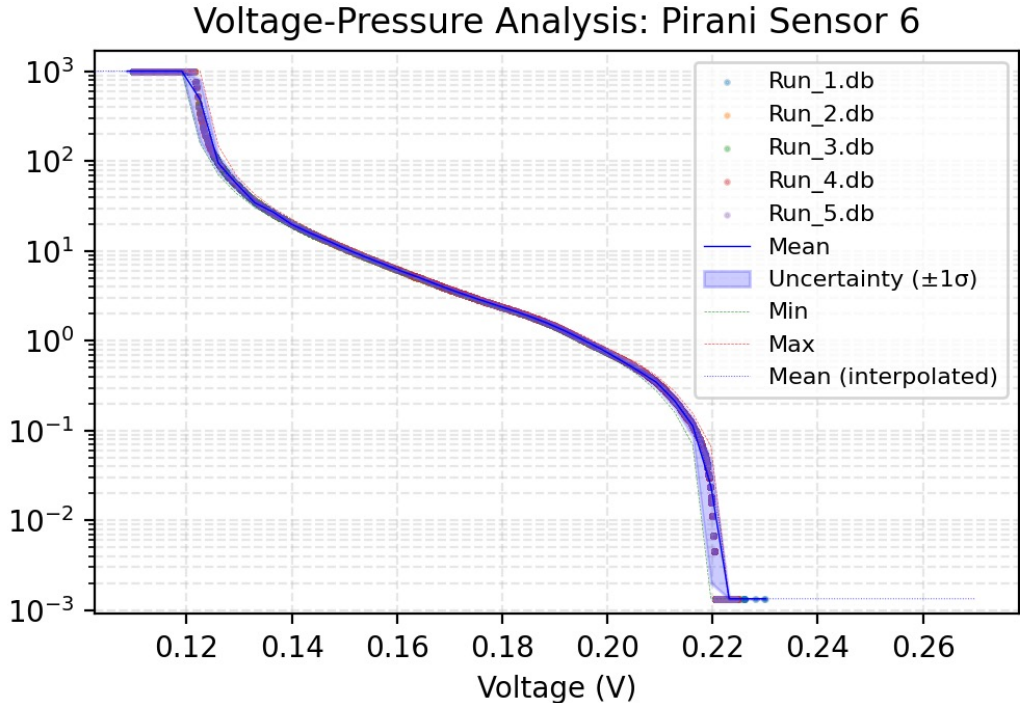


Batch 1 positioned at a  
distance to the proton beam

# Current Progress & Preliminary Results

Current state

Build test setup → Baseline characterization → Controlled irradiation → Evaluate radiation effects



Preliminary Baseline Results



Irradiated Sensors waiting for clearance

# Outlook



## Next steps:

- Evaluation of irradiated sensors
- Standardized Framework



## Future Tasks:

- Improved vacuum setup
- Expand readout to other types of sensors
- Automatization of evaluation process
- Irradiate 4<sup>th</sup> batch with higher radiation dose

# Thanks!

Especially to my supervisors and contributors:

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Maciej Ostrega (EP-DT-DI)

Xavier Pons (EP-DT-DI)

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Marc Carrichon and Bayram Dinger (EP-DT-DI Workshop)

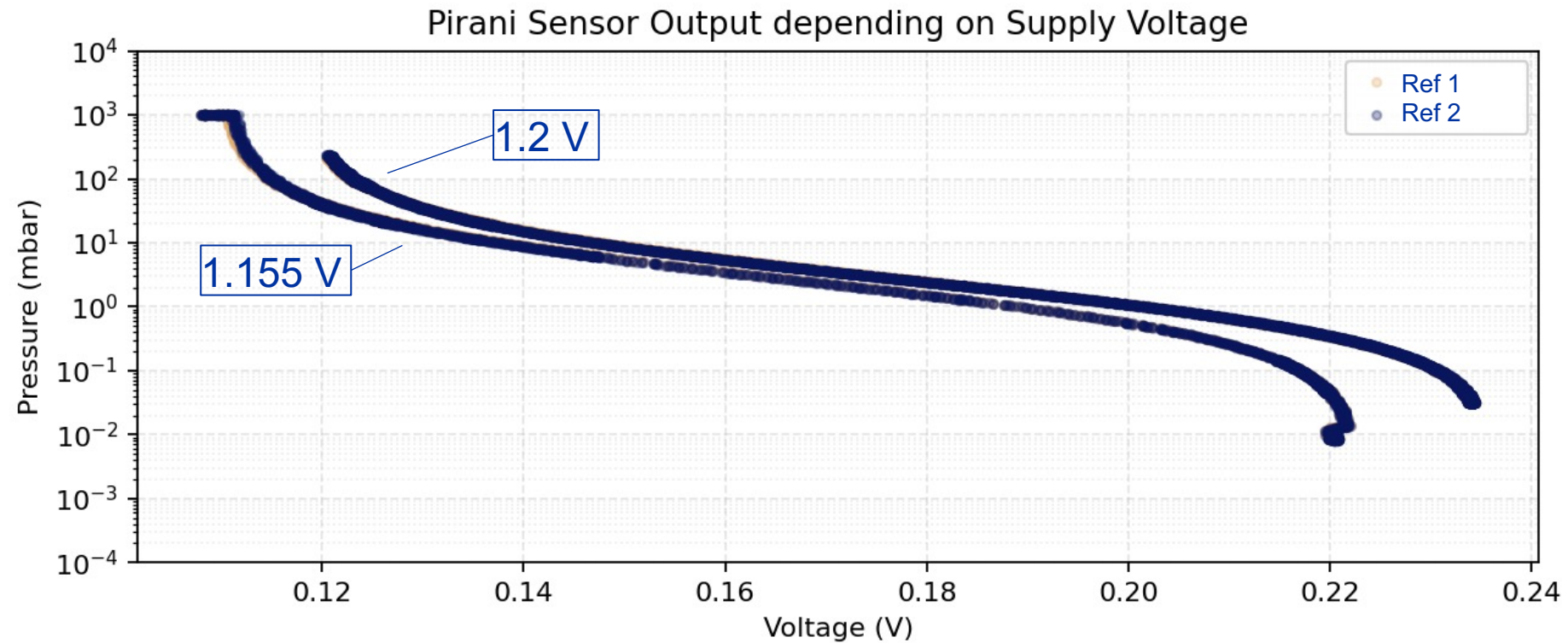
Wil Vollenberg (TE-VSC-SCC)



[home.cern](http://home.cern)

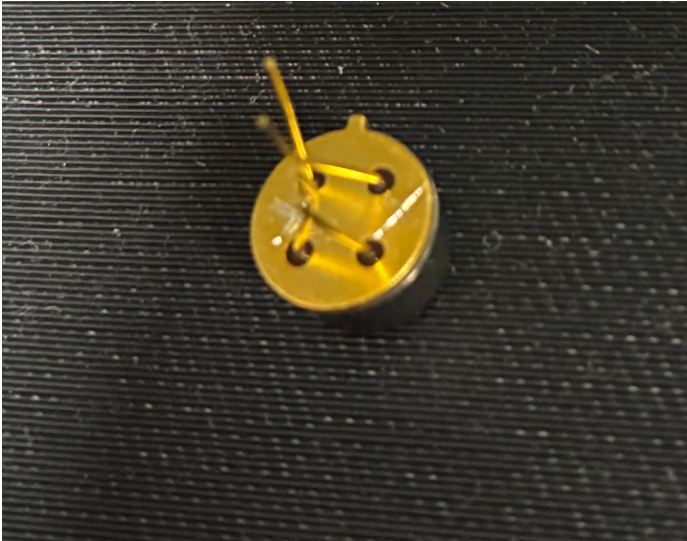
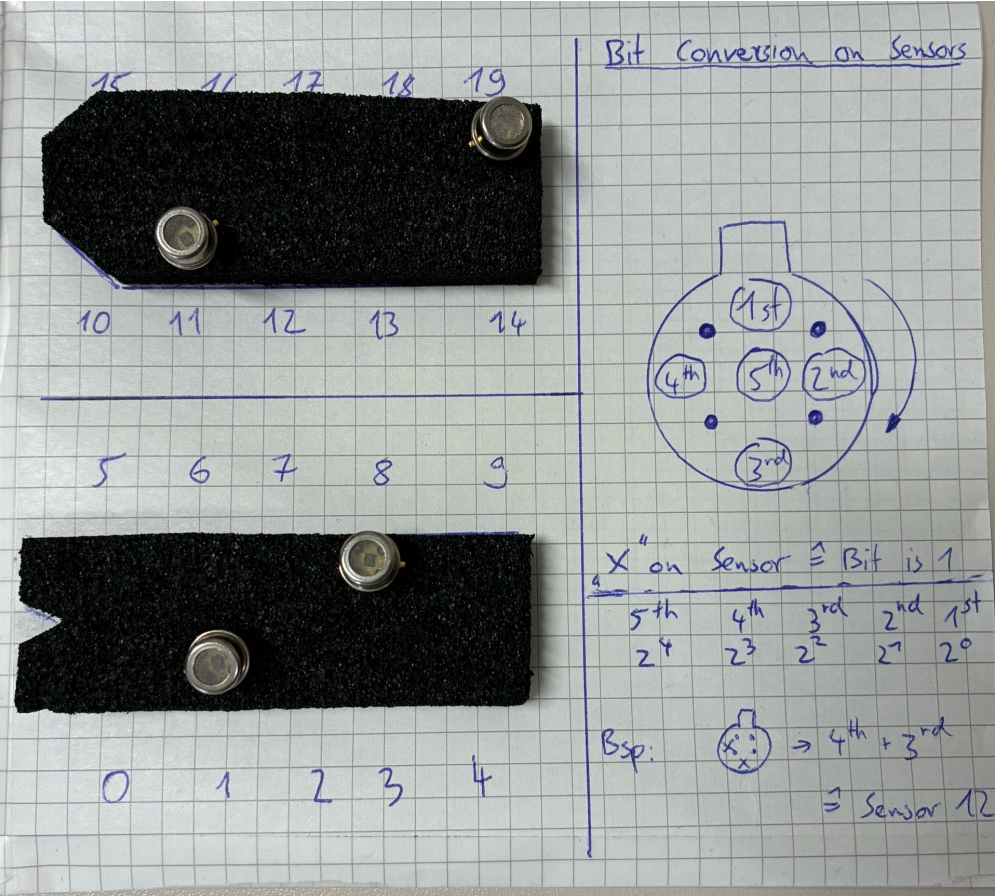
# Backup Slides

# Supply Voltage Dependence





# Sensor Identification



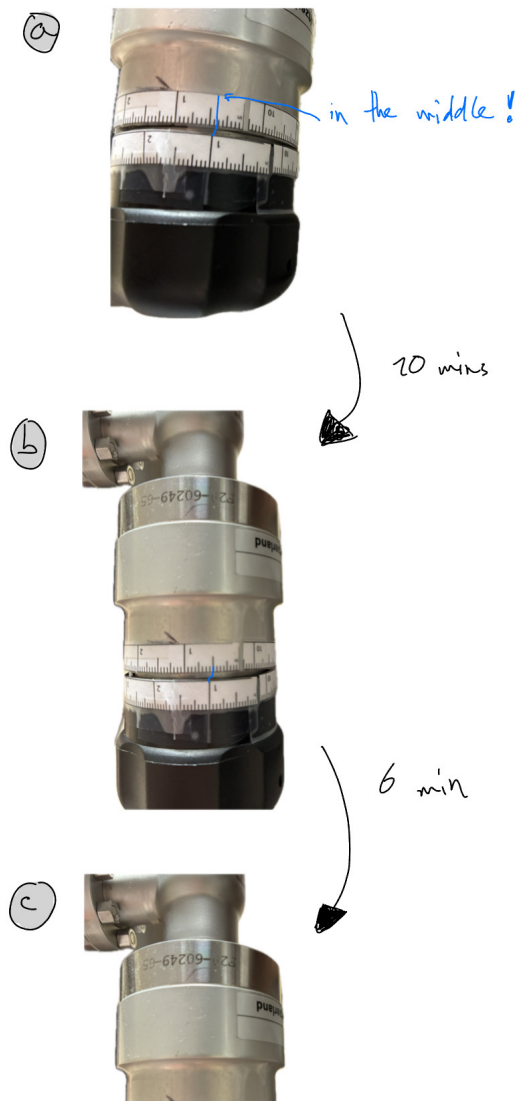
Binary Marking on Sensor

Dedicated Sensor Positions and Explanation of Marking

# Needle Valve Settings



Attached Scale on Needle Valve



Excerpt of the Settings for Test Rounds